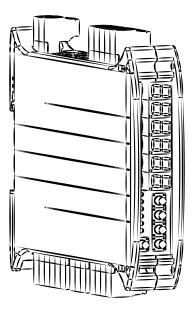


# **DGT1SP** Digital weight transmitter

## **USER MANUAL**

ENGLISH



Firmware version 01.19.xx



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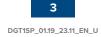
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**4** DGT1SP\_01.19\_23.11\_EN\_U

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Optimized layout for A4 print.





Dear Customer,

Thank you for purchasing a DINI ARGEO product.

This manual contains all the instructions for a correct installation and commissioning of the high speed DGT1SP digital weight transmitter. While thanking you for purchasing this product, we would like to draw your attention to some aspects of this manual.

This booklet provides useful information for the correct operation and maintenance of the scale to which it refers;

it is therefore essential to pay the greatest attention to all those paragraphs that illustrate the simplest and safest way to operate.

It is recommended that you carefully follow the instructions for programming the weight transmitter; performing actions not indicated in this manual could compromise the proper functioning of the scale.

The utmost care has been taken in compiling this manual, but reports of any inaccuracies are always welcome.

The transmitter is covered by warranty and MUST NOT BE TAMPERED WITH BY THE USER under any circumstances. Any attempt at repair or modification may expose the user to the danger of electric shock and voids any warranty conditions, relieving the Manufacturer from all liability.

Any problem with the product must be reported to the manufacturer or to the retailer where it was purchased. In any case, always TURN OFF THE POWER SUPPLY before any installation or repair operation.







#### Installation requirements

Observe the following conditions for correct installation of the transmitter and of the load receiver:

- Flat, level support surface.
- Stability and absence of vibrations.
- Absence of aggressive dusts and vapours.
- Absence of draughts.
- Make sure that the platform is levelled or that the load cells are evenly supported.
- Moderate temperature and humidity (15°C 30°C and 40% 70%).
- Do not install in an environment where there is a risk of explosion.
- All transmitter connections must be made in accordance with applicable regulations in the area and environment of installation. Observe the electrical precautions listed in the section "Electrical precautions".
- Ensure that it is correctly earthed, see the relevant section "Earthing of the system".
- Do not perform welding when the load cells have already been installed.
- If necessary, use watertight sheaths and fittings to protect the load cell cables.
- Any junction boxes must be watertight.
- Anything not expressly described in this manual constitutes improper use of the equipment.





## **Electrical precautions**

- Use a regulated mains supply within  $\pm\,10\%$  of the rated voltage.
- The electrical protections (fuses, etc.) are the responsibility of the installer.
- Observe the recommended minimum distances between cables of different categories (see table on page 10).
- The following cables must comply with the maximum permissible lengths (see table on page 10), they must be shielded and must be inserted alone in metal conduits or pipes:
  - the load cell extension cables;
  - the signal amplifier cables;
  - the cables for connecting the serial ports;
  - the analog output cables.
- The cell or amplifier cables must have an independent input in the electrical panel. They must be connected (if possible) directly to the terminal block of the transmitter without passing through the conduit with other cables.
- Fit "RC" filters:
  - on the contactor coils;
  - on the solenoid valve coils;
  - on all devices that produce electrical interference.
- If condensation can occur inside the weight transmitter, it is advisable to keep the equipment powered at all times.
- Connections to load cells and any external device must be as short as possible.
- The cable ends (connectors, leads, terminals, etc.) must be installed correctly; the cable shielding must be kept intact until close to the connection point.
- If the transmitter is placed inside an electrical panel, a shielded cable must also be used for the power supply.







#### RECOMMENDED DISTANCES AND CABLE CLASSIFICATION

	Category I	Categor	y II	Categ	jory III	Category IV
Distance	≥ 100 ≥ 200 ≥ 500	) mm	≥ 100 ≥ 500		≥ 50	0 mm
Classification	Fieldbus, LAN network (PROFIBUS, Ethernet, Devicenet). Shielded data cables (RS232). Shielded cables for analog digital signals < 25 V (sensors, load cells). Low voltage power sup- ply cables (< 60 V). Coaxial cables.	DC supply cable voltage > 60 V 400 V. AC supply cable voltage > 25 V 400 V.	and < es with	Power supp with voltage Telephone c	e > 400 V.	Any cable subject to lightning danger.

#### MAXIMUM ALLOWED LENGTHS

Load cell	RS232	RS485	Analog output
50 metres with 6 x 0.25 mm <sup>2</sup> cable; 100 metres with 6 x 0.5 mm <sup>2</sup> cable.	15 m with baud rate up to 19200.	1200 m with shielded 2 x 24 AWG twisted pair with outer braid + aluminium strip.	CURRENT: 100 metres with $2 \times 0.25 \text{ mm}^2$ cable; 150 metres with $2 \times 0.5 \text{ mm}^2$ cable; 300 metres with $2 \times 1 \text{ mm}^2$ cable. VOLTAGE: 50 metres with $2 \times 0.25 \text{ mm}^2$ cable; 75 metres with $2 \times 0.5 \text{ mm}^2$ cable; 150 metres with $2 \times 1 \text{ mm}^2$ cable.





## Earthing of the system

For correct earthing and optimal system operation, the transmitter, load cells, junction box, if any, and weighing structure must be earthed.

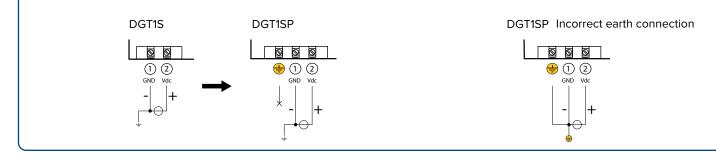
#### TRANSMITTER

The earth connection must be made via the appropriate terminal. The cable cross-section must be less than 2.5 mm<sup>2</sup>. The transmitter must be powered by a dedicated power supply with earth reference. Do not connect EARTH and GND terminals together!

#### i

If you want to use the DGT1SP to replace a transmitter without a dedicated earth terminal (e.g. DGT1S), you can make the earth connection using only the "GND" terminal and leaving the "EARTH" terminal free.

Attention: this type of connection excludes the additional circuit for protection against electrical noise.



#### LOAD CELLS AND JUNCTION BOX

The connection must be made by connecting the earth cables to the earth bar (cables that must have a cross-section of at least 16 mm<sup>2</sup>); finally, connect the earth bar to the earth post with a cable having a cross-section of at least 50 mm<sup>2</sup>.

#### EXAMPLES:

- If more load cells are connected to the transmitter through a junction box, the cable shield from the transmitter and the cell cable shields must be connected to the earth socket of the junction box (refer to the junction box manual) and the junction box must be earthed using a copper cable with a cross-section of not less than 16 mm<sup>2</sup>.
- If the load cell is connected directly to the transmitter (without using the junction box), the cell cable shields must be connected to the earthing point (or earth bar).
- If the weighing system involves large and/or outdoor structures (weighbridges, silos, etc.) and the distance between the junction box and the weight transmitter is greater than 10 m, connect the cell cable shields to the earth socket in the junction box.

#### WEIGHING STRUCTURE

Earth the weighing structure and/or any unconnected structures (e.g. silos that release material onto the weighing structure) using cables with a cross-section of not less than 16 mm<sup>2</sup>.

Also connect the upper part with the lower part of each cell by means of a copper braid with a cross-section not less than 16 mm<sup>2</sup> (refer to the earthing examples on page 12 and page 13).

#### SERIAL CABLES AND CONNECTED INSTRUMENTS

Connect the serial cable shield to the earthing point (or earth bar) inside the panel. To avoid any undesired effects, the earth reference of the connection cable, power supply and transmitter must be at the same potential.





#### **GENERAL NOTES:**

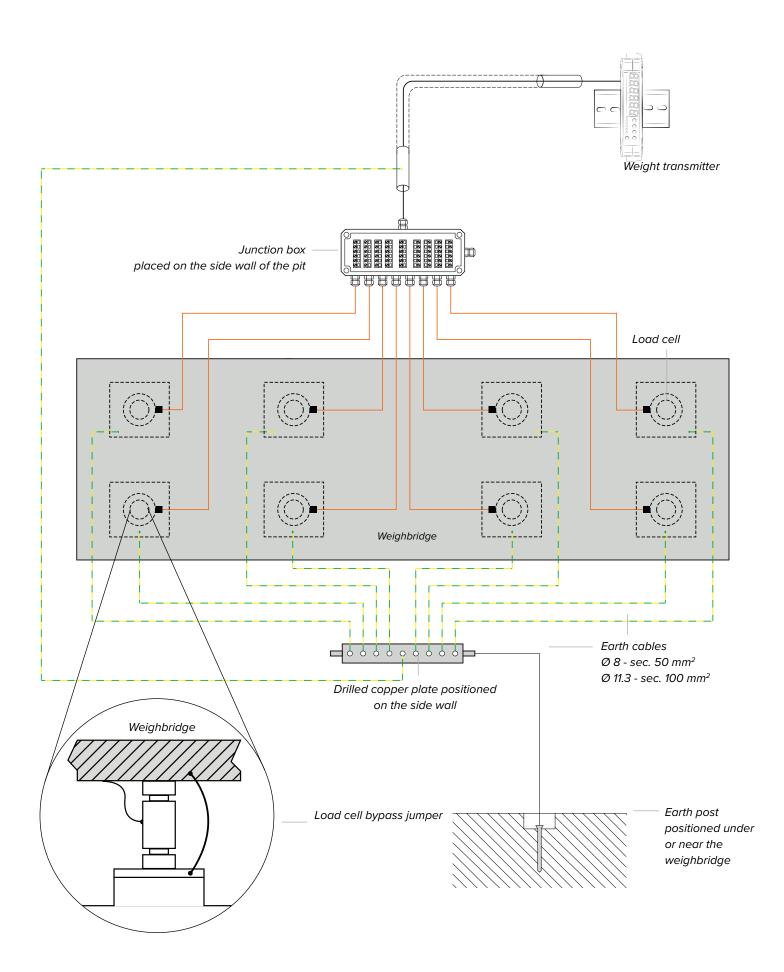
- All earth cables must be of suitable length, so as to obtain an overall resistance of the earthing system of less than 1 Ω.
- If the weighing system involves large and/or outdoor structures (weighbridges, silos, etc.):
  - the earth connection must be made by connecting the earth cables to an earth bar and the earth bar to the earth post with a cable having a cross-section of not less than 50 mm<sup>2</sup>;
  - the thickness of the cables must be greater (50 mm<sup>2</sup> instead of 16 mm<sup>2</sup> and 100 mm<sup>2</sup> instead of 50 mm<sup>2</sup>), because the voltages at stake are greater (e.g. lightning);
  - the earth post must be placed at a distance of at least 10 m from the structure.
- If the load receiver is more than 10 m from the transmitter, we recommend using the SENSE line and load cells equipped with a (SENSE) compensation circuit.







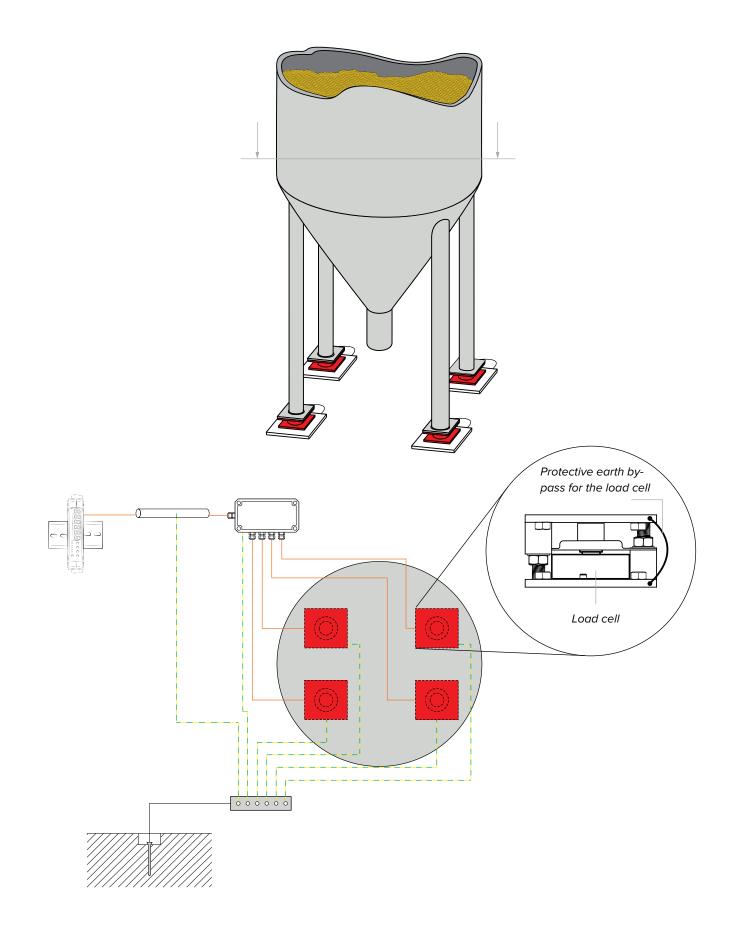
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## **Technical features**

POWER SUPPLY	12 - 24 Vdc LPS or with class 2 power supply.
MAXIMUM ABSORPTION (without load cells)	DGT1SP: 1 W DGT1SP-AN: 2 W DGT1SP-PB: 2 W DGT1SP-ETHIP, DGT1SP-PRONET, DGT1SP-ETHCAT, DGT1SP-MODTCP: 4 W DGT1SP-COPEN, DGT1SP-DEVNET: 4 W
OPERATING TEMPERATURE	From -10°C to +40°C.
DISPLAY DIVISIONS	10000e, 2 x 3000e for legal weighing, expandable up to 800,000 for internal use (with a minimum cell signal of 1.6 mV/V).
CONVERSION SPEED	Up to 4800 conv. / sec with single channel.
MINIMUM VOLTAGE PER DIVISION	0.3 $\mu$ V (approved transmitter); 0.03 $\mu$ V (non-approved transmitter).
COUNTING RESOLUTION	1,500,000 points (with input signal 3 mV/V).
DISPLAY	6 digits, h 8 mm (0.3").
SIGNALS	6 status indicator LED lights.
KEYPAD	mechanical with 5 keys.
TARE FUNCTION	Subtraction possible over the entire range.
LOAD CELL POWER SUPPLY	5 Vdc, 250 mA.
LOAD CELL CONNECTION	6 wires or 4 wires.
CONNECTABLE CELLS	Up to 16 350 $\Omega$ cells.
CASE	Made of plastic (ABS), suitable for DIN rail mounting (EN 60715 - DIN43880) or wall mounting.
SERIAL OUTPUTS	<ul> <li>1 half duplex RS485 bidirectional port on terminal (versions DGT1SP, DGT1SP-AN).</li> <li>1 PROFIBUS port on DB9 connector (DGT1SP-PB* version);</li> <li>2 ETHERNET ports (versions DGT1SP-ETHIP*, DGT1SP-MODTCP*, DGT1SP-ETHCAT*, DGT1SP-PRONET*);</li> <li>1 CANOPEN port on 5-pole terminal (DGT1SP-CANOP* version);</li> <li>1 DEVICENET port on 5-pole terminal (DGT1SP-DEVNET* version).</li> <li>1 USB port (micro USB type B) + Virtual COM (Device).</li> <li>* Fieldbus models are not equipped with port 485.</li> </ul>
OUTPUTS / INPUTS	<ul> <li>4 photomosfet NO or NC outputs: max 60 Vdc 0.5 A max / 48 Vac 0.5A;</li> <li>2 configurable inputs (bidirectional optocouplers): 12 - 48 Vdc; Input reading and output update time: 1 msec;</li> <li>16-bit analog output (DGT1SP-AN version). Current: 0 - 20 mA / 4 - 20 mA. Voltage: 0 - 5 Vdc, 0 - 10 Vdc. The maximum applicable resistance on the current output is 300 Ω while the minimum applicable resistance on the voltage output is 1 kΩ.</li> </ul>
LOAD CELL SENSITIVITY	Maximum sensitivity of the connectable load cells: 6 mV/V.
FIELDBUS UPDATE RATES	Up to 120 Hz.
CERTIFICATIONS	Indicated on the EC Declaration of Conformity of the product.



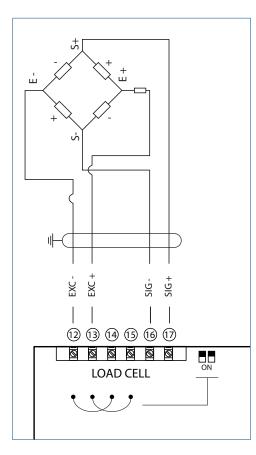


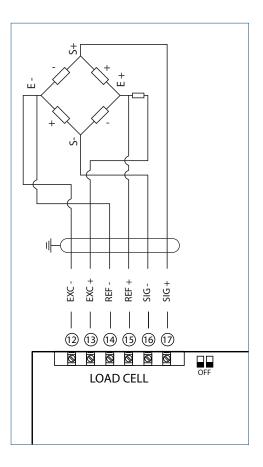
## Load cell installation

After carrying out the instructions for the platform or load receiver, the shielded cable from the cell must be properly connected to the terminal block of the transmitter (see section "Wiring diagrams").

The transmitter has one channel for 6-wire connection to load cells (using the REFERENCE).

The REFERENCE allows you to compensate for any voltage drop on the section of cable connecting the transmitter to the load receiver. It is especially useful when the distance between the transmitter and the load receiver is more than 10 metres, or in high-resolution applications.





**4-WIRE CONNECTION** 

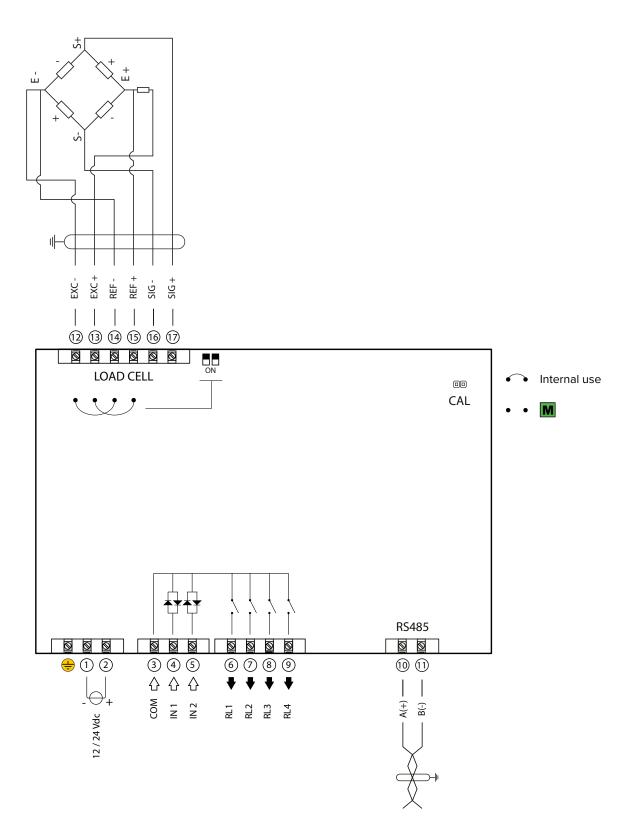
**4-WIRE CONNECTION** 





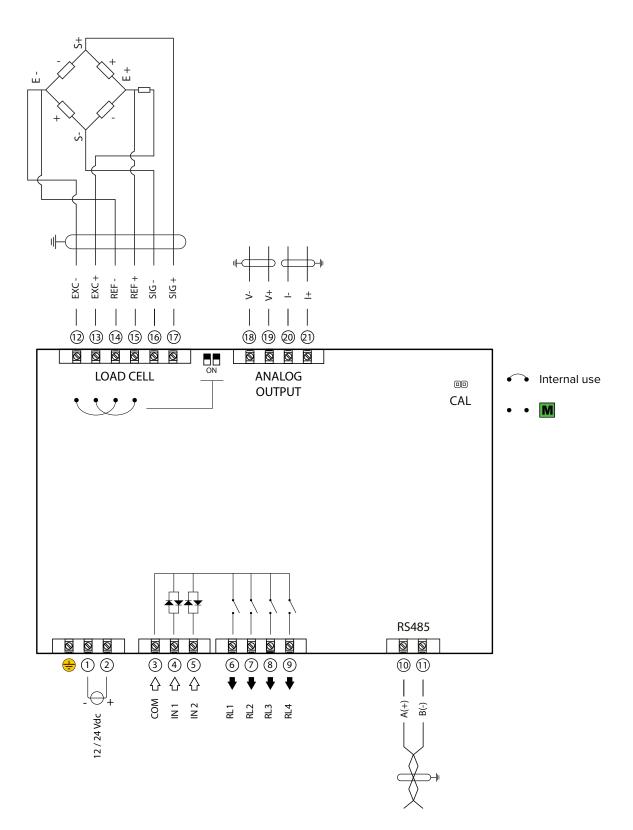


#### **DGT1SP**



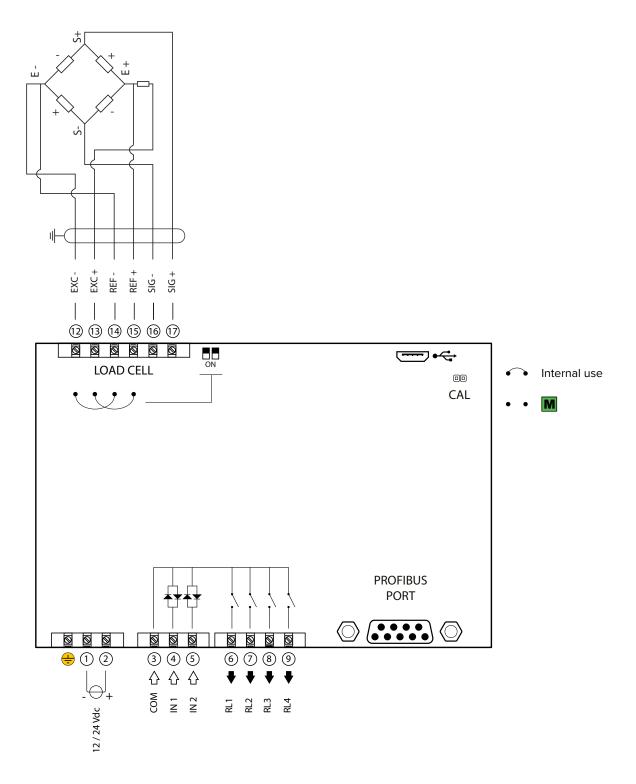












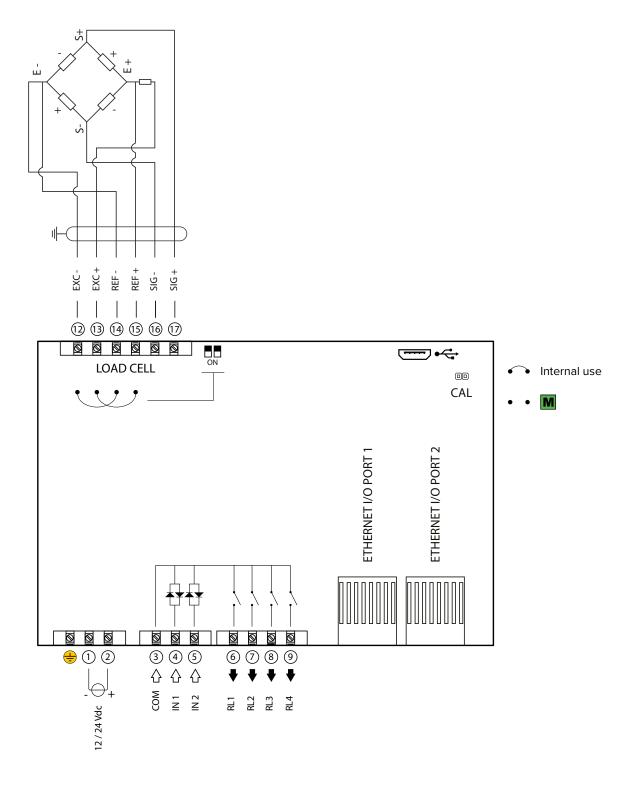


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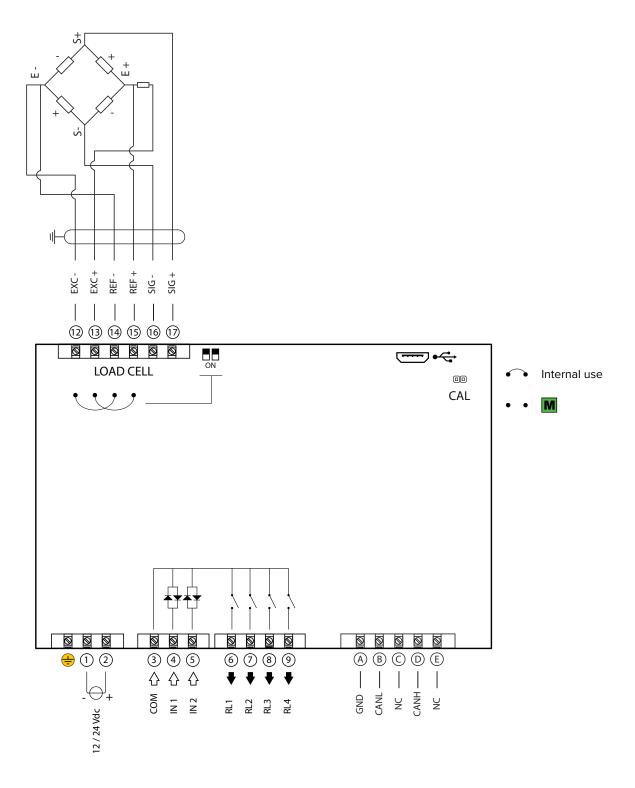
### DGT1SP-ETHIP, DGT1SP-ETHCAT, DGT1SP-PRONET, DGT1SP-MODTCP





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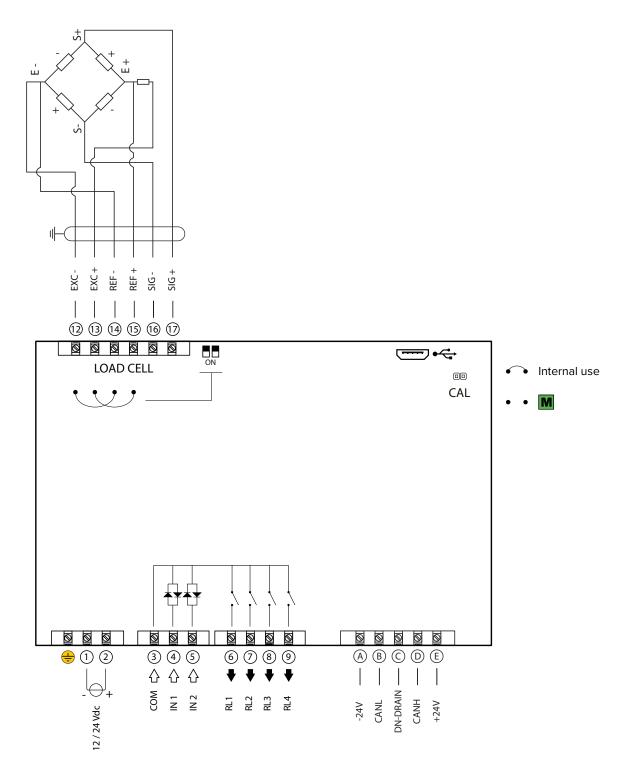


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#### **DGT1SP-DEVNET**

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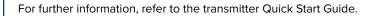


Symbol	Description	Number	Description
•	Semi-automatic zeroing. Decreases the selected digit.	1	Gross weight on zero.
	Semi-automatic tare. Increases the selected digit.	2	Unstable weight.
	Activates the function. Selects the digit to be changed.	3	A tare is active.
		4	A special function is active.
4	Confirms a value. Prints / Transmits data.	5	Output 1 is active.
С	Reboots the transmitter.	6	Output 2 is active.

#### Quick menu

The transmitter is equipped with a quick menu, through which you can program the main parameters of the scale. To enter the quick menu, follow the procedure below:

- 1. Reboot the transmitter.
- 2. Press the key when the display shows 888888.









The advanced menu contains all the transmitter configuration parameters for the most advanced adjustments.

## Access to the advanced menu and saving the changes

**1.** Reboot the transmitter.

Press the key when the display shows 888888.

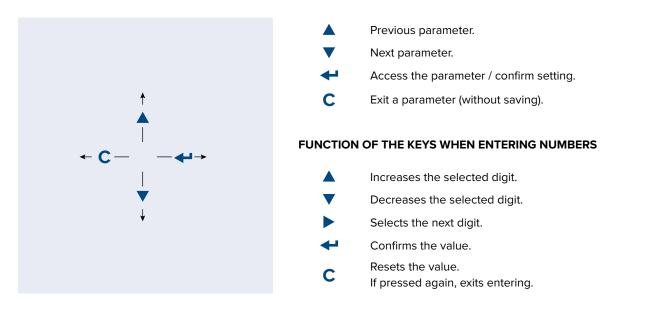
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#### HOW TO EXIT THE SETUP AND SAVE CHANGES

**1.** Press C several times, until the display shows "SAUE?".

Press + to save or C to exit without saving.

#### Function of the keys in the menu



In the menu description on the following pages the  $\overrightarrow{V}$  symbol indicates repeated pressing of the  $\overrightarrow{V}$  key until the parameter indicated is reached.



Complete menu on pages **24 - 25** 

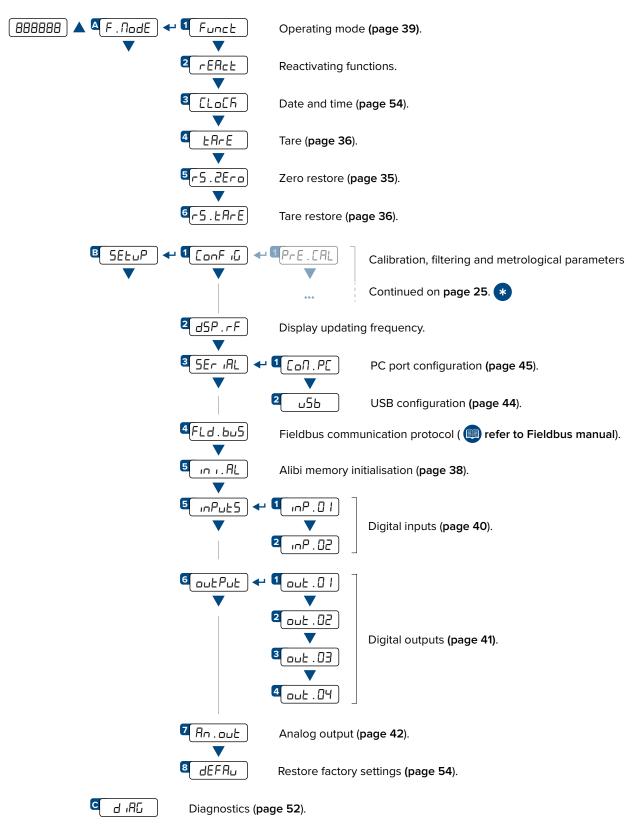


Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



#### Block diagram of the menu





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the 💙 key.

Indicates repeated pressing of

LEGEND:

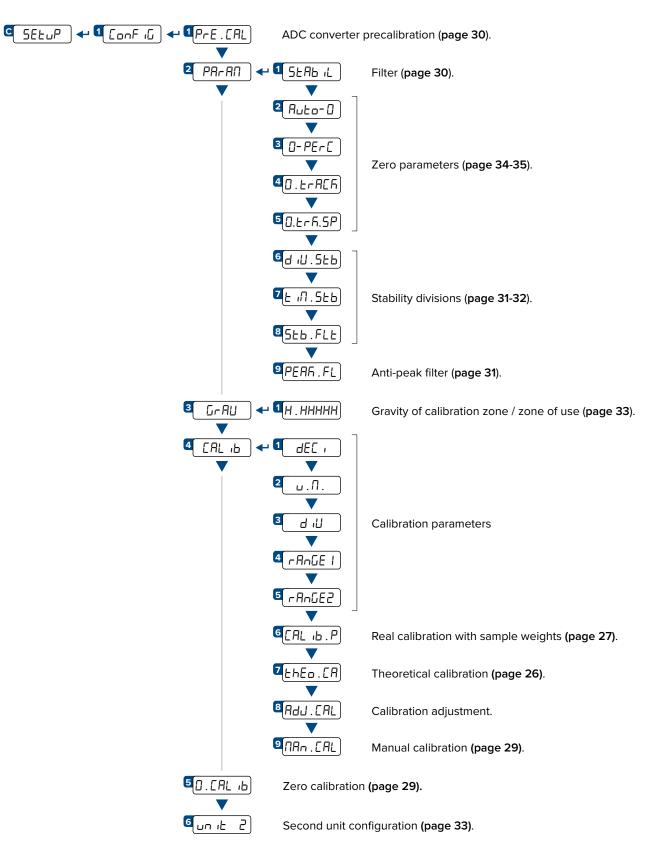
Parameter visible only under certain conditions. Parameter or menu subject to approval.

Ö Default value of the parameter.



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Complete menu on pages **24 - 25** 

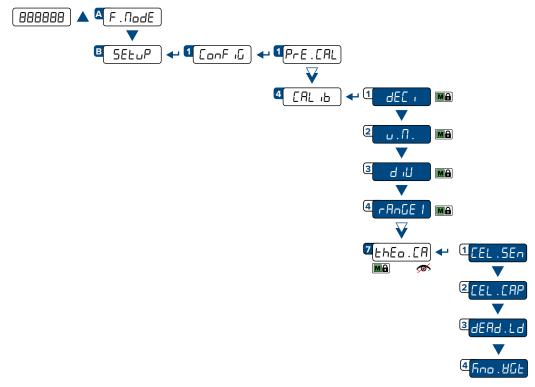


Press the **k**ey during the startup procedure. SAVING THE PARAMETERS:

Press the C key several times, until the display shows SRUE?. Press the ← key to confirm.



#### **Theoretical calibration**



#### CALIBRATION PROCEDURE:

1. Set the calibration parameters:

- dEL = Number of decimals.
- $\cup .\Pi$ . = Unit of measurement ( $h_{i}$ ,  $b_{i}$ ,  $b_{i}$ , L, Lb).
- d ו = Minimum division.
- -AnGE I = Maximum range.

#### 2. Set the cell data:

- $5E_{n}$ . [EL = Cell sensitivity (given by the average mV/V value of cells).
- *LEL* .*LRP* = Total capacity of the cells (given by the sum of the capacities of each cell).

3. Enter the weight value of the structure in the dERd.Ld parameter. If you do not know this value, enter "0".

4. If the structure contains a quantity of material whose weight value is known (e.g. full silo), enter this value in the hand. Hot parameter.

#### 5. Application of theoretical calibration:

Press the C key to exit the calibration menu. The display shows b L CRLP. Press the + key to confirm the use of the theoretical calibration, or the C key to cancel.

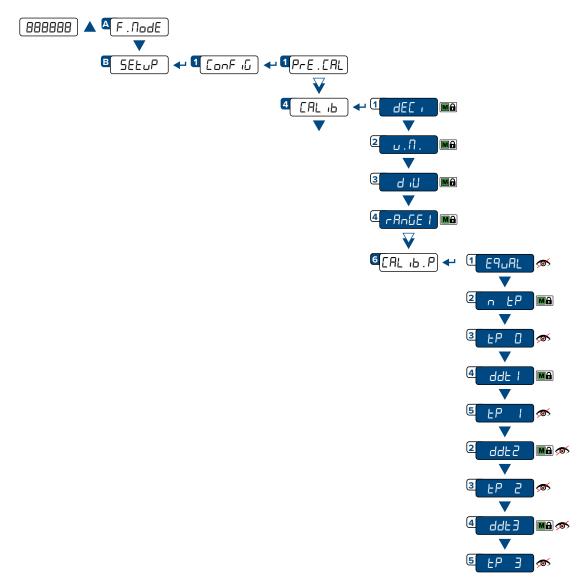
Parameter or menu subject to approval.







### **Calibration with sample weights**



#### CALIBRATION PROCEDURE:

**1.** Set the calibration parameters:

- dEL = Number of decimals.

  - d ו = Minimum division.
  - -AnGE I = Maximum range.
- 2. Acquire the calibration points (continued on next page)



Ο

Complete menu on pages **24 - 25** 

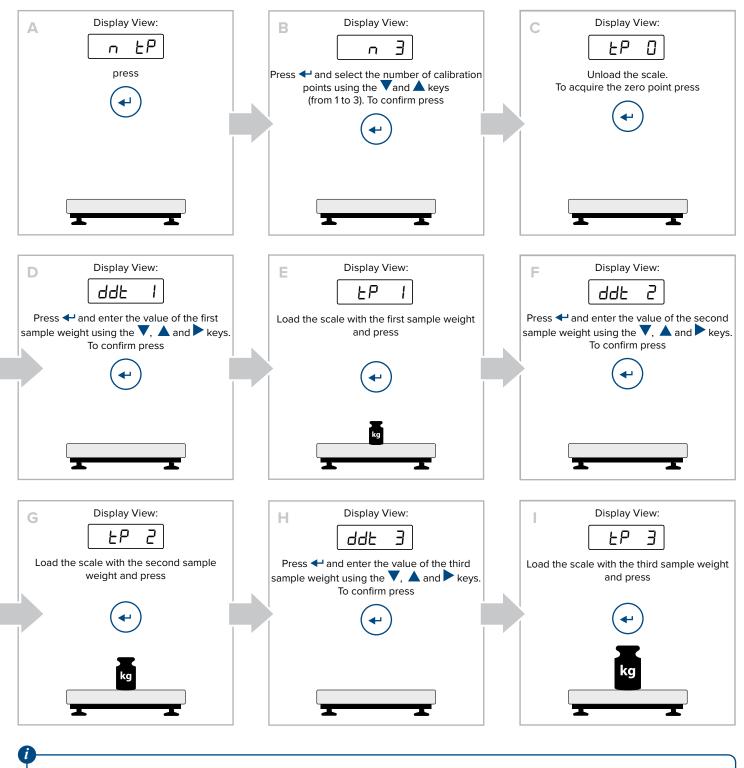


Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



#### 3. Acquire the calibration points:



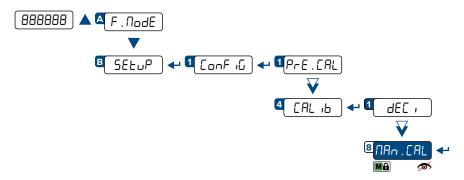
For successful calibration, the value of the largest sample weight must be at least 50% of the capacity.







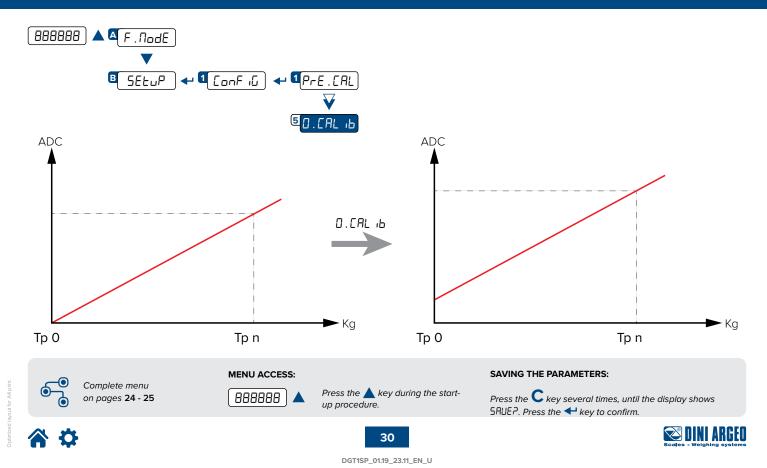
#### **Manual calibration**



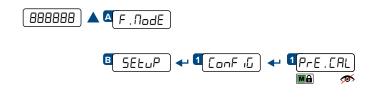
If you know the number of ADC converter points for a known weight (for example if you want to copy the calibration from one transmitter to another) the calibration points can be entered manually:

- 1. The display shows nod. Pot, and then the last calibration point.
- 2. Using the ▲ and ▼ keys, select the calibration point you want to enter / change (from 0 to 8). Press the ← key to confirm.
- 3. The display shows <code>BE fubble</code>, use the ▲, ▼ and ▶ keys to enter the weight value. Press the ← key to confirm.
- 4. The display shows P<sub>□</sub> mE5, use the ▲, ▼ and ▶ keys to enter the converter points value.
   Press the ← key to confirm.





### **ADC** converter precalibration

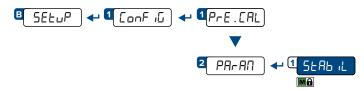


For manufacturer use only

#### **Filter and stability**

#### **Filter adjustment**





Filter	Updating frequency (Hz)	Response time (ms)	Use
FI	5	5000	High resolution or
F 2	10	2500	Oscillating loads
\$ FЭ	20	1000	Simple weighing
FЧ	40	450	
FS	80	300	Dosing
F 6	160	150	
F٦	325	50	High-speed weight
			transmission

In the case of an approved transmitter, it is possible to select only filter  $F \exists$ .

The filter affects the speed of the PC port only if RLL . NRH mode has been selected.



Indicates repeated pressing of the 💙 key.



Parameter visible only under certain conditions.

Parameter or menu subject MA to approval.

Default value of the parameter.



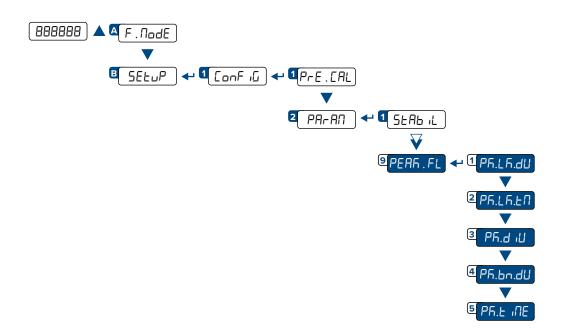


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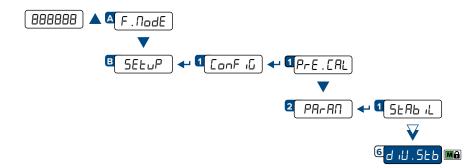
## Anti-peak filter

The transmitter has an additional filter for the elimination of sudden weight peaks (e.g. shocks or falling material). The following parameters, opportunely configured, allow you to eliminate the peak by blocking the weight for its entire duration. The weight is blocked if it remains within the number of divisions set in  $PF_{..}LF_{..}dU$  for the time set in  $PF_{..}LF_{..}E\Pi$  and is subsequently unblocked if the weight deviates from the blocking value for a number of divisions greater than  $PF_{..}d_{..}U$  (or  $PF_{..}b_{..}.dU$ ) or if the time set in  $PF_{..}L_{..}IE$  has elapsed.



#### **Stability detection divisions**

It is possible to decide that tare and zero functions (from keypad or serial command / PLC) are performed only if the weight is stable.



The value 0 disables the stability control.From 0 to 99.By entering a value other than 0, you enable stability control. $\clubsuit = 02.$ Enter the number of deviation divisions beyond which the transmitter detects instability. $\blacksquare = 02.$ 



Complete menu on pages **24 - 25** 

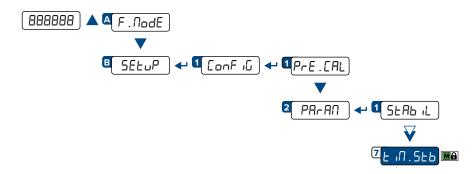


Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **4** key to confirm.



#### **Stability detection time**

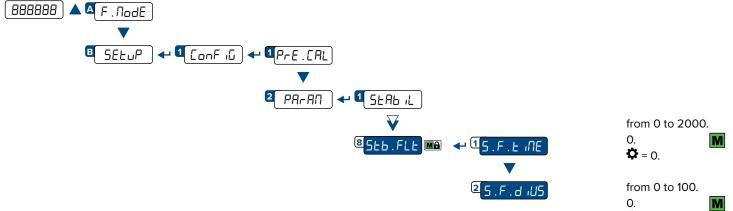


If the weight remains within the number of divisions set in  $d_1U.5b$  for the time set in this parameter, the weight is stable. 500.

Enter the value in ms. In case of approved transmitter, the value is fixed at 500 ms.

from 10 to 10000. 500.

#### Additional filter for stability detection



Additional filter that locks the weight if it oscillates around a value for a maximum of 10 divisions. The weight is unlocked if the value increases/decreases for the number of divisions set in the parameter S.T.DIVS for a time value greater than the time set in the parameter S.T.TIME. The value 0 disables the filter.

**☆** = 0.



Indicates repeated pressing of the key.

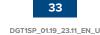


Parameter visible only under certain conditions.

Parameter or menu subject to approval.

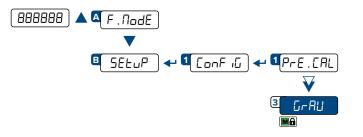
Default value of the parameter.







#### Gravity



From 9.7500 / to 9.84999.

This parameter allows you to correct the gravity acceleration value. Before calibration, set the value of the calibration zone. Next, set this value to the value of the zone of use. Any difference between the two values will be automatically compensated.

In the case of an approved transmitter, the value is read-only.

#### EXAMPLE:



Calibration zone Italy g = 9.80543



Zone of use Brazil g = 9.77623 **1.** Before calibration, in the  $G \cap RU$  parameter enter the value 9.80543.

2. Calibrate the transmitter.

**3.** Before using the transmitter, in the G = RU parameter enter the value 9.77623.



Complete menu on pages 24 - 25



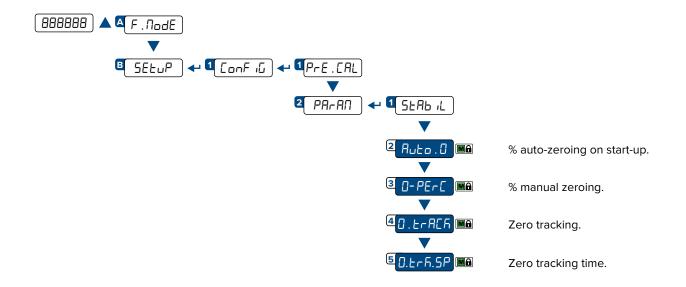
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **+** key to confirm.



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#### **Reset functions and parameters**



#### Auto-zeroing on start-up

🝳 Ruto. 0 🕶 🖣 d (SRb 🗘	Disabled.	
	Enabled, enter in $\mathcal{L}$ . <i>PErC</i> the % value of the capacity.	from 0 to 50%. from 0 to 10%.

#### Maximum percentage of manual zeroing



Indicates the weight value that can be zeroed by key or command. The value is expressed as % of the full scale. For example: if the scale has a full scale (r AnGE I) of 1000 kg, by setting 3% it is possible to zero up to 30 kg. The value 0 disables the ZERO key and the zeroing commands.

from 0 to 50%. from 0 to 2%. **\$** = 2%.

LEGEND:

the 💙 key.

Indicates repeated pressing of

under certain conditions.

Parameter visible only

 $\mathbf{\mathbf{A}}$ 

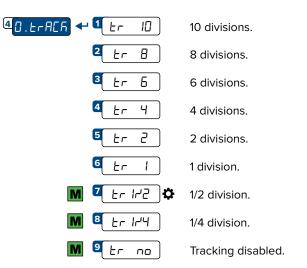
Parameter or menu subject MA to approval.

Default value of the parameter.



## Zero tracking

This menu allows to set zero tracking, i.e. the compensation parameter of the thermal drift of the scale; the set value corresponds to the number of divisions that is reset to zero in the fixed time of 1 second.



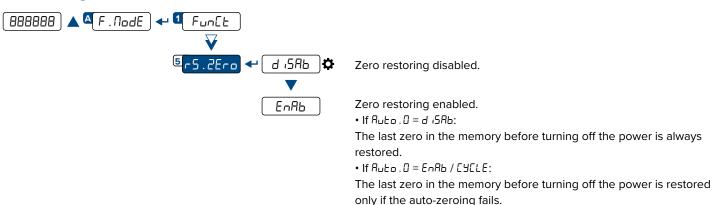
#### **Zero tracking time**

5 D.Er R.SP

Once stability is reached, the transmitter waits for the time set in this parameter before bringing the weight back to zero (if it is within the divisions set in D.  $E_{F}REF$ ).

from 100 to 5000. 1000. M **‡** = 1000.

#### **Restoring zero**



## Semi-automatic zeroing

By pressing the V key, or sending the zero command, the transmitter zeroes the gross weight on the scale. For a moment the display shows "2Ero" and then it shows 0 (gross weight).

The semi-automatic zeroing cannot be performed if:

- The weight on the scale is greater than the zero capacity (D.  $PE_{r}C$ ).
- The weight is unstable.



MENU ACCESS: Complete menu on pages **24 - 25** 



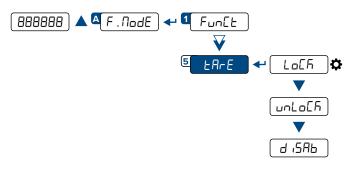
SAVING THE PARAMETERS:

Press the  ${\sf C}$  key several times, until the display shows 



### Tare functions and parameters

### Tare mode



Tare blocked. When the gross weight drops to 0, the tare remains engaged.

Tare unlocked. When the gross weight drops to 0, the tare is cleared.

Tare disabled.

### Semi-automatic tare

By pressing the  $\blacktriangle$  key, or sending the tare command, the transmitter sets as tare the weight on the scale. For a moment the display shows " $\pounds R_F E$ " and then it shows 0 (net weight). The **3** light indicates that the net weight is shown on the display.

The semi-automatic tare cannot be performed if:

- The weight is less than one division.
- The weight is overloaded.

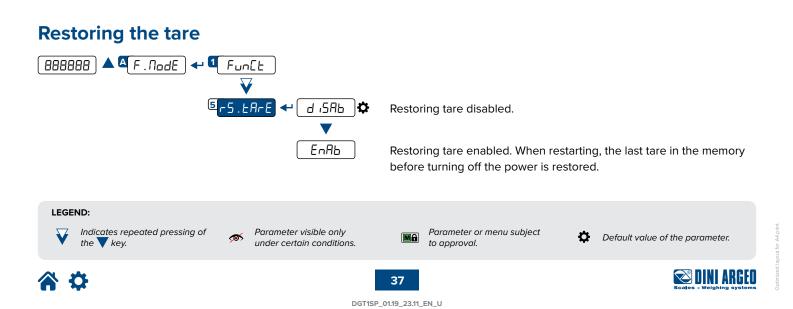
## **Predetermined tare**

By holding down the  $\blacktriangle$  key, or by means of the predetermined tare command, it is possible to enter a tare value manually. For a moment the display shows "- $t\Pi$ -" and shows the tare present (or 0 if no tare is present). Enter the tare value and press  $\checkmark$  to confirm.

### **Clearing the tare**

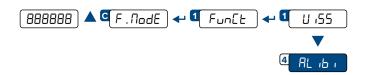
The tare can be cleared in different ways:

- By unloading the scale and performing a semi-automatic tare.
- By entering a predetermined tare value of 0.
- If the weight is negative, pressing the  $\checkmark$  key.



The alibi memory allows you to store the weight values transmitted to the computer for further processing and/or data integration. The stored values can then be retrieved from the PC port or directly on the display of the transmitter for later checking.

## **Enabling the alibi memory**



## Saving a weighing operation in the alibi memory

A weighing operation is stored after receiving the **PID** serial command (see **"Serial commands" page 57**) or after pressing the **+** key. The transmitter transmits on the PC port the gross weight, the tare and an ID code that uniquely identifies the weighing. The ID has the following format:

• rewrite number: 5-digit number (from 00000 to 00255) indicating the number of complete rewrites;

• weighing number: 6-digit number (from 000000 to 131072) indicating the weighing number in the current rewrite.

Each time it is saved, the weighing number is increased by 1; when it reaches the value 131072, it starts again from 000000 and the rewrite number is increased by 1.

#### Example

If the weighing that has been saved is as follows:

#### PIDST,1, 1.000kg, 1.000kg,00126-131072

The next one will be:

#### PIDST,1, 1.000kg, 1.000kg,00127-000000

A weighing operation can only be saved if the weight  $\geq$  0, stable and valid (not underloaded or overloaded). To store the weighing operation by key, the function must be active (see **"Reactivating printing" on page 53**). In addition, if the transmitter is approved, the weight must exceed 20 divisions.

If these conditions are not met:

• the response to the PID command will have "NO" instead of the ID (PIDST,1, 1.000kg, 1.000kg,NO);

• there is no transmission when the  $\blacktriangleleft$  key is pressed.





Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



# Reading the alibi memory

#### FROM THE TRANSMITTER (MANUAL)

By pressing the key you can read a saved weight:

you will be asked to enter the rewrite number "rEB. rd" (from 0 to 255) and the ID number "rd" (from 0 to 131072).

The weighing data are shown. Use the igvee and igwed keys to scroll through the following information:

- " ${\it Lh}$  . X", where X indicates the scale number.
- " $\Pi$  YY", where YY indicates the unit of measurement (FL, L, L or Lb).
- "Gro55", followed by the gross weight.
- "EArE / EArEPE", followed by the tare value.

Press the  $\mathbf{C}$  key to return to weighing.

The weighing of an ID can only be verified if:

it has a rewrite number equal to the current alibi memory number and a weighing number ≤ the last value received with the PID command;
it has a rewrite number ≥ 0, but 1 less than the current alibi memory value, and a weighing number greater than the last value received with the PID command.

#### FROM PC

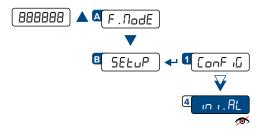
To read a weighing operation from a PC, see the serial command "**READING A WEIGHING OPERATION IN THE ALIBI MEMORY**" on page 57.

#### FROM PLC

To read a weighing operation from a PLC, refer to the Modbus and Fieldbus protocol manuals.

If the alibi memory is empty, when the  $\blacktriangleright$  key is pressed the display shows "Enpty" for one second and returns to weighing mode. If an invalid ID is entered, the display shows "and returns to weighing mode.

### Initialising the alibi memory



Mot visible if the transmitter is approved.

This operation deletes all saved weighing operations; it is not possible to delete a weighing operation individually.

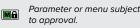
**39** 



Indicates repeated pressing of the key.



Parameter visible only under certain conditions.

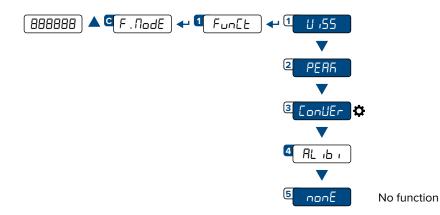


Default value of the parameter.





## **Use functions**



## **High resolution**

Weight display in high resolution (x10). Press the ▶ key to activate or deactivate the function. When the weight is displayed in high resolution, the 4 light is lit. In the case of an approved transmitter, the high-resolution weight display is automatically deactivated after 5 seconds.

### **Peak detection**

РЕЯЋ

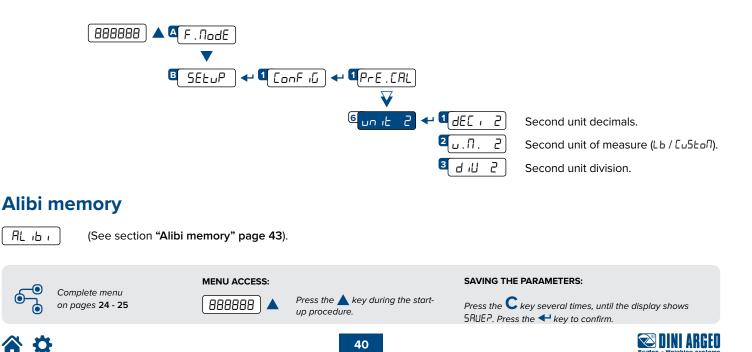
55، لا

Detection of the maximum weight value during a time interval. Press the  $\blacktriangleright$  key to activate the function. The display shows "-*PERF-*" every 5 sec and the transmitter shows the maximum weight reached since the function was activated. To deactivate the function press the  $\triangleright$  again, the display shows "*PERFoF*" for a moment and shows the instantaneous weight again.

### **Converting units of measurement**

conUEr

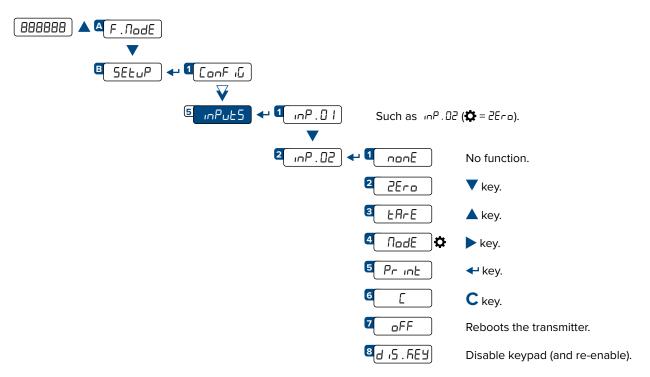
Converting the scale unit of measurement. Press the key to convert the weight to pounds. By holding down the key, you can enter a free conversion factor, which will be multiplied by the weight. **Example:** To make the instrument convert kg  $\rightarrow$  m<sup>3</sup> of water, enter the value 0.997 as conversion factor. The key can be used to switch from the main unit of measurement to the secondary unit at any time. When the secondary unit of measurement is displayed, the **4** light is lit. The display of the secondary unit of measure can be configured in the parameter unit  $c^2$ :



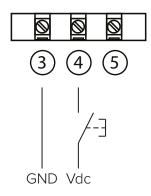
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# Input configuration

The indicator has 2 configurable inputs (bidirectional optocouplers).



#### INPUT CONNECTION:



The input is activated when there is a potential difference between terminals 4 - 5 (IN1 and IN2) and terminal 3 (INCOM). The inputs are bidirectional, therefore it is possible to invert GND and Vdc.

#### LEGEND:

Parameter visible only under certain conditions.

Parameter or menu subject MA to approval.



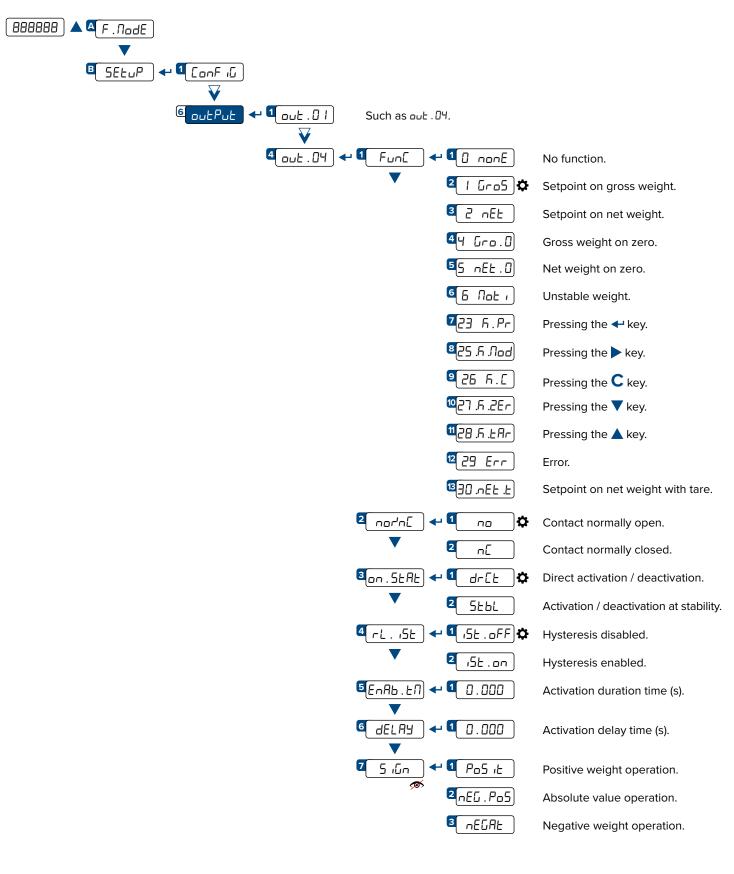


41



## **Output configuration**

The indicator has 2 programmable outputs (photomosfet).



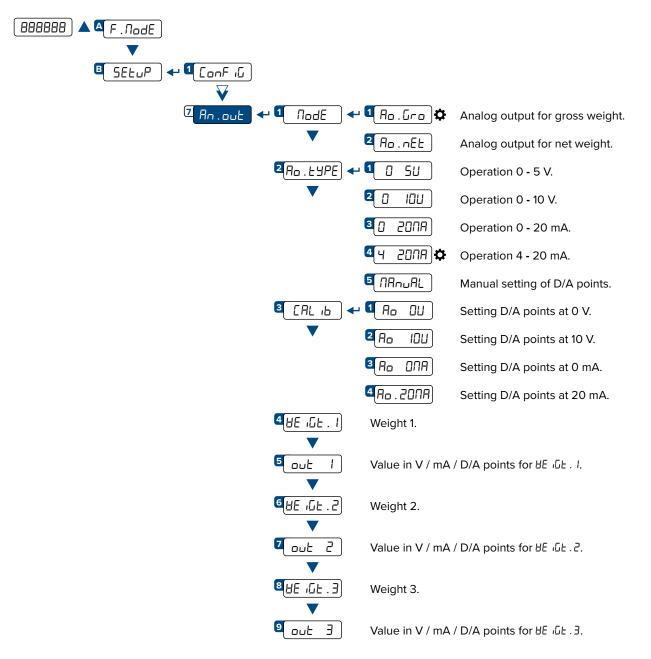
MENU ACCESS:

Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **↔** key to confirm.



The DGT1SP-AN model has an analog output in voltage (0 - 5 / 0 - 10 Vdc) or current (4 - 20 / 0 - 20 mA).



This menu allows an advanced configuration of the analog output.

Ø

For simple configurations, it is recommended to use the quick menu (Ref. Quick Start Guide).

Parameter visible only

under certain conditions.



LEGEND:

the 💙 key.

Indicates repeated pressing of



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MA

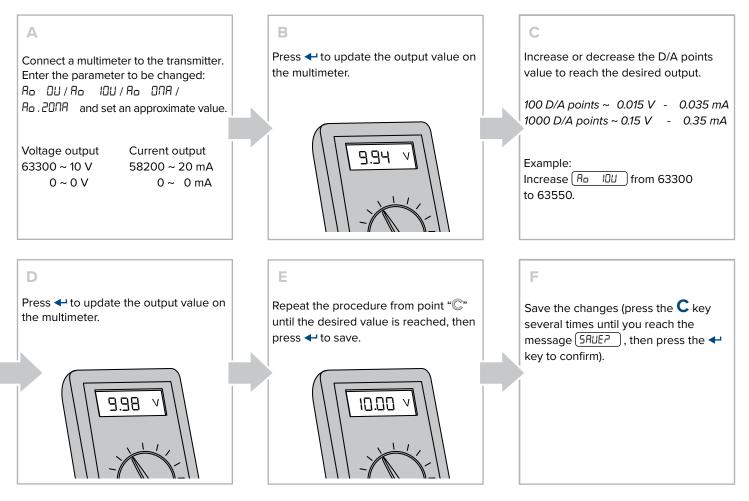
Parameter or menu subject

to approval.

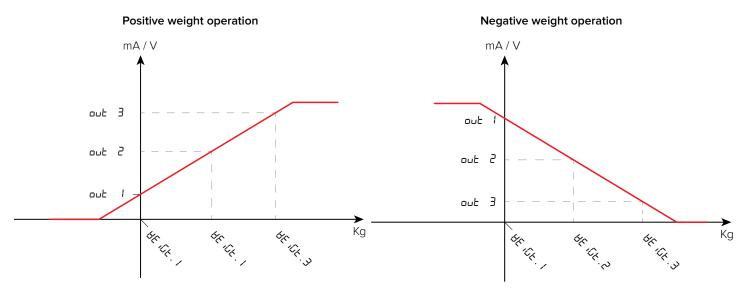
Ö

Default value of the parameter.

#### CALIBRATION PROCEDURE:



#### ANALOG OUTPUT GRAPHS:



<u>Current:</u> 21 (+) and 20 (-). <u>Voltage:</u> 19 (+) and 18 (-).



Complete menu on pages **24 - 25**  MENU ACCESS:

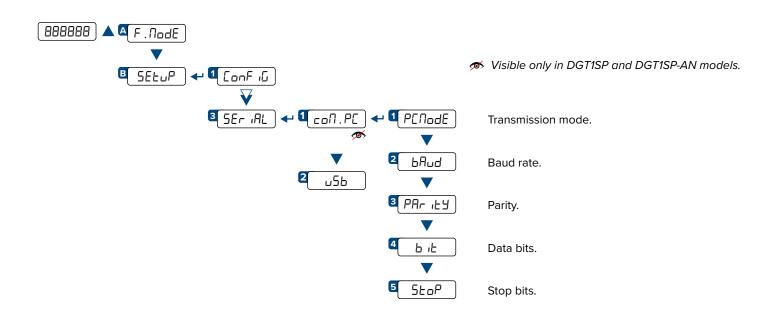
Voltage or current operation is determined by the connection to the transmitter terminals:

Press the key during the startup procedure. SAVING THE PARAMETERS:

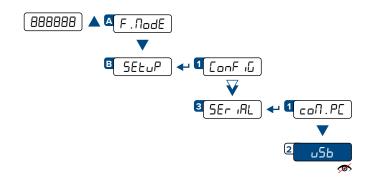
Press the **C** key several times, until the display shows SRUEP. Press the **+** key to confirm.



All models are equipped with a micro-USB port that is always accessible for transmitter configuration and diagnostics. The DGT1SP and DGT1SP-AN models also have an RS485 port.



## **Configuration of the USB port**



Useful for the configuration of the instrument from PC with Dinitools.

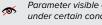
Mot visible in DGT1SP and DGT1SP-AN models.



LEGEND:

the 💙 key.

Indicates repeated pressing of



Parameter visible only under certain conditions.

Parameter or menu subject MA to approval.

**Ö** Default value of the parameter.



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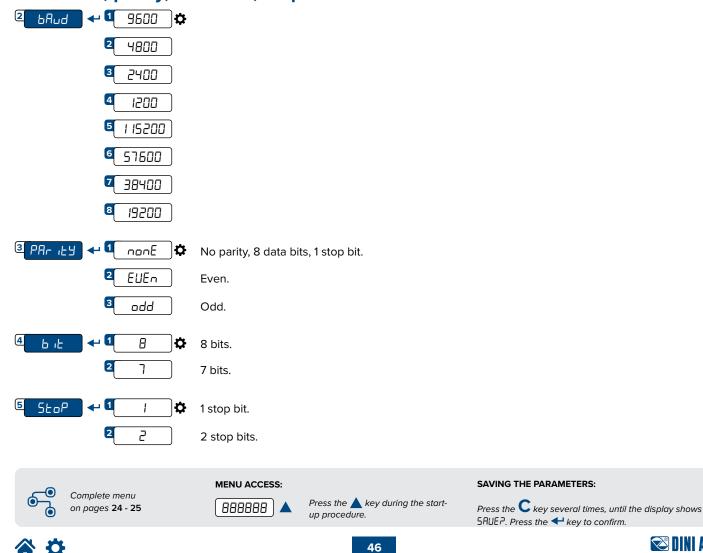
# Configuration of the 485 port (PC port)

## **Transmission mode**

I PENodE ← I ondE	Transmission on demand.
2 rEPE.6	Transmission of the weight on DINI ARGEO 6-digit repeater.
😻 🕄 Pr. in. 5E	Standard string transmission when the <table-cell-rows> key is pressed.</table-cell-rows>
\star 4Pr. in.EH	Extended string transmission when the $\blacktriangleleft$ key is pressed.
5 485	Transmission with 485 protocol (enter the 485 address of the transmitter).
6 Nodbu5 🗘	Transmission with Modbus protocol (refer to the Modbus protocol manual).
ZALL . NAH	Continuous high speed weight transmission for conversion applications (single channel only)
🔹 🛿 🖁 RLL.SED	Continuous transmission of the standard string (select the transmission frequency, about 1 $\div$ 80 Hz).
\star 🛛 🖓 🛞 🛞	Continuous transmission of the extended string (select the transmission frequency, about 1 $\div$ 80 Hz).
😻 🏧 SERB.SE	Stable transmission of the standard string.
🔹 왭 SERB.EH	Stable transmission of the extended string.
*	

When selecting one of these protocols, you are asked if you want to display the 485 address at the beginning of the string: dEU . id <table-cell-rows> YES / no.

### Baud rate, parity, data bits, stop bits



🕿 DINI ARGEO

# **Standard string**

## [01]ST,GS, 0.0,kg<CR><LF>

Where:	
01	Transmitter code 485 (2 characters), only if communication mode 485 is enabled
ST	Scale status (2 characters): <u>US</u> - Unstable weight <u>ST</u> - Stable weight <u>OL</u> - Weight overload (out of range) <u>UL</u> - Weight underload (out of range)
,	Character ASCII 044
GS	Type of weight data <i>(2 characters)</i> <u>GS</u> - Gross <u>NT</u> - Net <u>VL</u> - Microvolts <u>RZ</u> - Converter points
,	Character ASCII 044
0.0	Weight (8 characters including the decimal point)
3	Character ASCII 044
kg	Unit of measurement (2 characters)
<cr><lf></lf></cr>	Transmission terminator, characters ASCII 013 and ASCII 010

# **Extended string**

<b>[01]1ST,1,</b> Where:	0.0,P1	20.8,	0,kg,01/02/19 11:12:13 <cr><lf></lf></cr>
01		Transmitter of	code 485 (2 characters), only if communication mode 485 is enabled
1		Number of t	ne active scale
ST		<u>US</u> - Unstabl <u>ST</u> - Stable v <u>OL</u> - Weight	0
,		Character A	SCII 044
0.0		Weight (8 ch	aracters including the decimal point)
,		Character A	SCII 044
РТ		Preset tare i	ndication
20.8		Tare (8 char	acters including the decimal point)
,		Character A	SCII 044
0		Character A	SCII 048
,		Character A	SCII 044
kg		Unit of meas	surement (2 characters)
,		Character A	SCII 044
01/02/19 11:	:12:13	dd/mm/yy h	h:mm:ss (only with REXD command and optional clock card)
<cr><lf></lf></cr>		Transmission	n terminator, characters ASCII 013 and ASCII 010





# Serial commands

By selecting the PC port on demand mode (andE), you can communicate with the transmitter via serial commands. For each command received, the transmitter emits a string containing the response (refer to the command description) or one of the following signals:

OK <crlf></crlf>	Command sent when sending a correct command. This response does not imply that the command is executed.
ERR01 <crlf></crlf>	Command sent correctly but followed by letters entered unintentionally (e.g. READF, TARES).
ERR02 <crlf></crlf>	Incorrect command data.
ERR03 <crlf></crlf>	Command sent not allowed (transmitter busy, or not used in the selected operating mode).
ERR04 <crlf></crlf>	Command sent non-existent.

If the 485 protocol has been selected, you must precede the command with the transmitter address (e.g. 01READ).

#### WEIGHT READING (standard string)

Format	R	Е	А	D	<cr lf=""></cr>
Response	Star	ndard	strin	ig <c⊮< th=""><th>R LF&gt;.</th></c⊮<>	R LF>.

#### WEIGHT READING IN HIGH RESOLUTION (X10)

Format	G	R	1	0	<cr lf=""></cr>	
Response	Stan	dard	string	with v	veight in res	olution x10 <cr lf="">.</cr>

#### MANUAL TARE

Format	Т	М	А	Ν	t	t	t	t	t	t
	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>								
Where		tttttt				tar	e val	ue		
Response	OK<	CR L	F> <b>(o</b>	r ERF	Rxx).					

By entering a manual tare value of 0, the tare on the scale is cleared.

#### DISABLING KEYPAD

Format	К	Е	Y	Е	D	<cr lf=""></cr>	
Response	OK<	<cr l<="" th=""><th>.F&gt; <b>(</b>o</th><th>r ERF</th><th>Rxx).</th><th></th><th></th></cr>	.F> <b>(</b> o	r ERF	Rxx).		

#### **READING INPUTS**

Format	I	Ν	PUn <crlf></crlf>						
Where	n	I	nput	(1 / 2)	).			_	
Response	I	Ν	Р	U	n	v	v	v	v
	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th colspan="3"></th></cr<>	LF>							
	ı	٦	Inpu	ıt nur	nber.				
			Inpu	ut sta	tus:				
Where	vv	vv	000	)1 = A	ctive	ctive. readir		ror.	

#### **EXTENDED WEIGHT READING**

Format	R	Е	Х	Т	<cr lf=""></cr>
Response	Exte	endeo	d strir	ng <c< th=""><th>R LF&gt;.</th></c<>	R LF>.

#### AUTOMATIC TARE

Format	Т	А	R	Е	[I]	<cr lf=""></cr>	]
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

Send the TAREI command to perform tare without stability control.

#### ZEROING

Format	Z	Е	R	0	[I]	<cr lf=""></cr>	
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

Send the ZEROI command to perform zeroing without stability control.

#### ENABLING KEYPAD

Format	К	Е	Y	Е	Е	<cr lf=""></cr>	
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

#### **READING OUTPUTS**

Format	0	U	Т	S	n	<cr< th=""><th>LF&gt;</th><th>]</th><th></th></cr<>	LF>	]							
Where	n	0	utpu	t (1 / 4	1).			-							
Response	0	U	Т	S	n	v	v	v	v						
	<cr< th=""><th>LF&gt;</th><th colspan="12"></th></cr<>	LF>													
	r	ı	Output number.												
			Out												
Where	vv	vv	000	)0 = N )1 = A F = C	ctive		ding (	error.							







**\*** 

#### PRESSING A KEY

Format	К	Е	Y	Р	х	х	<cr lf=""></cr>
	х	х		Key d	code.		
	0	0			7		
347	C	)1					
Where	0	2					
	0	3			μ		
	0	4		C			
						-	
Response	OK<	CR L	.F> <b>(</b> o	r ERF	Rxx).		

#### **RELEASING A KEY**

Format	К	Е	Y	R	<cr lf=""></cr>
Response	OK<	CR L	F> <b>(</b> 0	r ERF	₹xx).

#### BRIDGE BETWEEN THE SERIAL PORTS

KEYR commands in succession.

prolonged pressing of the key.

Format	В	R	Ι	D	G	Е	1	<cr lf=""></cr>
Response	OK<	CR L	.F> (o	r ERF	Rxx).			

To simulate pressing a key, you must send the KEYP and

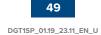
If more than 1.5 s pass after the KEYP command is sent, the transmitter will execute the function associated with

#### SCALE INFORMATION

Format	R	А	L	L	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>																	
	s	s	,	b	,	Ν	Ν	Ν	Ν	Ν	Ν	u	u	,	L	L	L	L	L	L	u	u	,
Response	Υ	Y	Т	Т	Т	Т	Т	Т	u	u	,	S	S	S	,	Α	А	Α	,	С	С	С	С
	,	,	R	R	R	R	R	-	I	Ι	Ι	Ι		I	<cr< td=""><td>LF&gt;</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></cr<>	LF>							
		SS		OL = ST =	= Unc = Ove = Stat = Uns	erload ble w	d. eight																
		b		Nun	nber	of the	e acti	ve so	ale.									-					
	NNI	NNN	Nuu	Net	weig	ht wi	th un	it of ı	neas	urem	ent.												
	LL	LLLL	uu	Gro	ss we	eight	with	unit c	of me	asure	emer	ıt.											
		ΥY		PT i	PT if a manual tare is present or "".																		
	TT	ТТТТ	ūu	Tare	Tare with unit of measurement.																		
Where		SSS		000 001	Scale status: 000 = scale weighing. 001 = entering a numerical value. 002 = scale in technical menu.																		
				000	inter )1 = 🚺		pres	sed:															
		ΑΑΑ			)2 = /																		
					)3 = 🕽 )4 = 🖣																		
					-																		
		ccc	2	0170 = C Code of last key pressed.																			
	R	RRR	R		t rew					o Alib	i me	mory											
				Last	t ID n	umbe	er sav	/ed to	o Alib	oi me	mory												



**A** 



#### **READING OF MICROVOLTS**

Format	М	V	0	L	
Response	Star	ndard	l strir	ng <cl< th=""><th>R LF&gt;.</th></cl<>	R LF>.

#### INITIALISING ALIBI MEMORY

Format	А	L	D	L
Response	ALD	LOK	/ ALC	DLNC

#### **READING OF CONVERTER POINTS**

Format	R	А	Z	F	]			
Response	Star	ndard	l strin	ig <cf< th=""><th>R LF&gt;.</th><th></th><th></th><th></th></cf<>	R LF>.			

#### WEIGHT READING WITH DATE AND TIME

Format	R	Е	Х	D	
Response	Exte	endeo	d strir	ng <c< th=""><th>R LF&gt;.</th></c<>	R LF>.

#### READING A WEIGHING OPERATION IN THE ALIBI MEMORY

Format	А	L	R	D	Х	Х	Х	Х	Х	-	Y	Y	Y	Y	Y	Y	<cr lf=""></cr>			
	b	,	L	L	L	L	L	L	L	L	L	L	u	u	,					
Response	Y	Y	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т	u	u	<cr< td=""><td>LF&gt;</td><td>]</td><td></td><td></td><td></td></cr<>	LF>	]			
			b		Sca	cale number.														
	LL	LLLL	LLLL	uu	Gro	cale number. iross weight with unit of measurement.														
Where		Ŷ	Ϋ́		"PT	if a n	าลทนส	al tar	e is p	rese	nt or	"".								
	TT	тттт	TTTT	Tuu	Tare	e with	unit	of m	easu	reme	nt.									

#### SAVING A WEIGHING OPERATION IN THE ALIBI MEMORY

Format	Ρ	Ι	D	<cr< th=""><th>LF&gt;</th><th>]</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>	]																	
	Ρ	I	D	s	Т	,	b	,	L	L	L	L	L	L	L	L	L	L	u	u	,	Y	Y
Response	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т	u	u	,	Х	Х	Х	Х	Х	-	Y	Y	Y	Y
	Y	Y	<cr< td=""><td>LF&gt;</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></cr<>	LF>																			
		I	b		Scale number.																		
	LL	LLLL	LLLL	uu	Gro	Gross weight with unit of measurement.																	
Where		Y	Ϋ́		"PT	if a r	nanua	al tar	e is p	resei	nt or	"".											
where	TT	тттт	TTTT	Гuu	Tare	e with	n unit	of m	easu	reme	nt.												
		XX	XXX		Rewrite number.																		
		YYY	YYY		ID number.																		

)—

The fieldbus protocol is described in the respective manual.





# **Modbus Protocol**

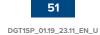
#### MODBUS REGISTERS FOR DATA READING (SINGLE SCALE)

Data	Register	DESCRIPTION		
Gross Weight	30001	Gross weight value		
	30002	Gross weight value.		
Net Weight	30003	Netweight value		
Net Weight	30004	Net weight value.		
Input status register	30005	Bit 15 (msb)Active channel.Bit 14Active channel.Bit 13No function.Bit 12No function.Bit 12No function.Bit 14No function.Bit 15Input no. 2 status.Bit 8 (sb)Input no. 1 status.Bit 7 (msb)Gross zero zone (0 = "outside zone 0"; 1 = "in zone 0").Bit 5Tare PT (1 = a preset tare is active).Bit 5Tare (1 = a tare is active).Bit 4Overload condition (0 = No; 1 = Overload).Bit 3Underload condition (0 = No; 1 = Underload).Bit 4Stability (0 = Unstable; 1 = Stable).Bit 1Gross weight sign (0 = "+"; 1 = "-").Bit 0 		
Command status register	30006	Last command received.         Bit 7 (msb)       Last command result.         Bit 6       Last command result.         Bit 5       Last command result.         Bit 4       Last command result.         Bit 3       Processed command count.         Bit 2       Processed command count.         Bit 1       Processed command count.         Bit 0       Processed command count.		
Output status register	30007	No function.         Bit 7 <sub>(msb)</sub> No function.             Bit 2       No function.         Bit 1       Digital output 1 status (0 = OFF; 1 = ON).         Bit 0 <sub>(lsb)</sub> Digital output 2 status (0 = OFF; 1 = ON).		
μV Channel 1	30111	μV value.		

This manual contains the main registers for reading data / sending commands. Refer to the Modbus protocol manual for a complete list of available registers.



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#### MODBUS REGISTERS FOR SENDING COMMANDS

Data	Register	DESCRIPTION		
		Main com	nands available:	
		Value	Command	
		00 Hex	No command	
		01 Hex	Zero	
		02 Hex	Tare	
Command	40001	03 Hex	Predetermined tare	
		0A Hex	Setting setpoint 1	
		0B Hex	Setting setpoint 2	
		19 Hex	Setting digital outputs	
		22 Hex	Rebooting the transmitter	
Parameter 1	40002	First command parameter. The parameter is always expressed as an absolute value (no decimal / sign).		
	40003			
Parameter 2	40004	Second command parameter. The parameter is always expressed as an absolute value (no decimal / sign).		
	40005			

#### EXAMPLE 1

To reset the weight on the scale:

2. Set the command in register 40001

Byte	Value	
1	00 Hex	
2	01 Hex	

#### EXAMPLE 2

To set a predetermined tare of 1000kg:

Set the value in parameter 1 (registers 40002-40003)
 Set the command in register 40001

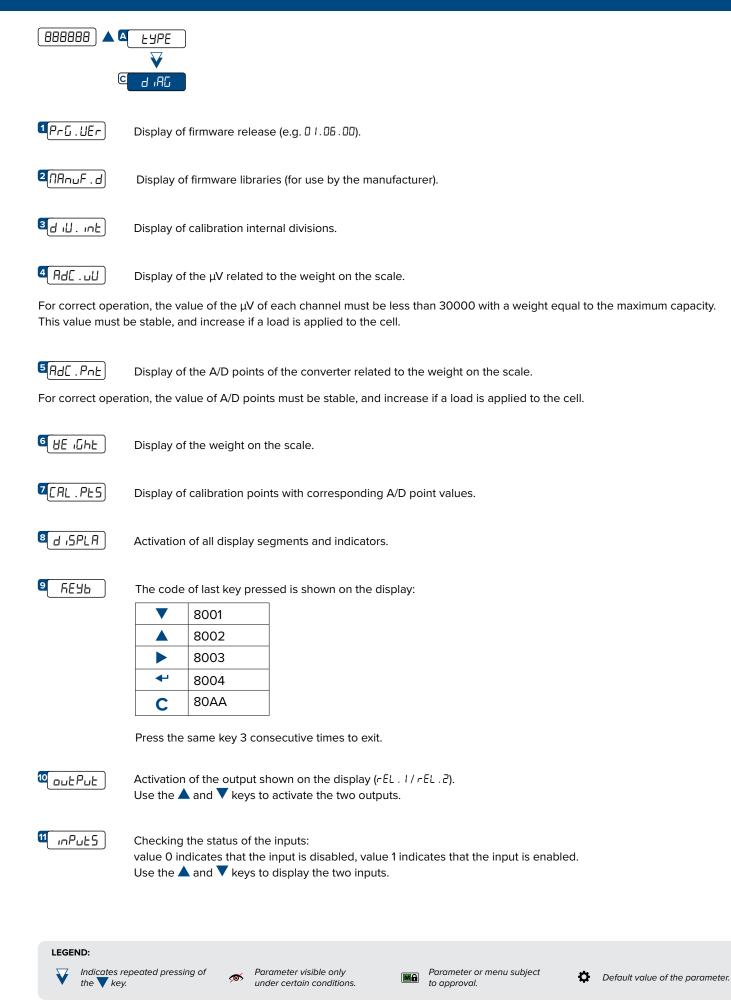
Byte	Value
1	00 Hex
2	03 Hex
3 <sub>(MSB)</sub>	00 Hex
4	00 Hex
5	03 Hex
6 <sub>(LSB)</sub>	E8 Hex

This manual contains the main registers for reading data / sending commands. Refer to the Modbus protocol manual for a complete list of available registers.





### Diagnostics











Analog output test.

Use the  $\blacktriangle$ ,  $\bigtriangledown$ ,  $\triangleright$  keys to enter the D/A point value of the analog output. Press the  $\leftarrow$  key to confirm and update the V / mA value of the analog output.

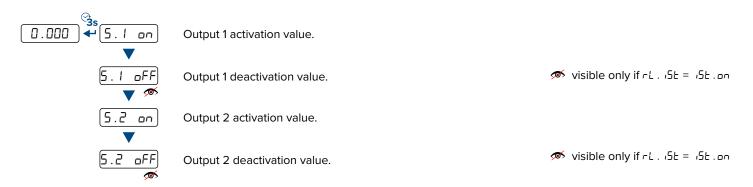


Display of transmitter serial number.

徑[EL . [hh] Voltage value test (used to display load cell error "EEL . Err").

## **Programming the Setpoints**

In weighing mode, if the output functions ( 1 Gro55 / 2 nEE) have been set correctly, pressing 🗲 for 3 seconds will enter the setpoint programming menu:



Once you have entered the desired values, press C. The display shows "5½ pr E" and returns to weighing mode.



Complete menu on pages **24 - 25** 



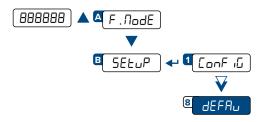
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **4** key to confirm.



54 DGT1SP\_01.19\_23.11\_EN\_U

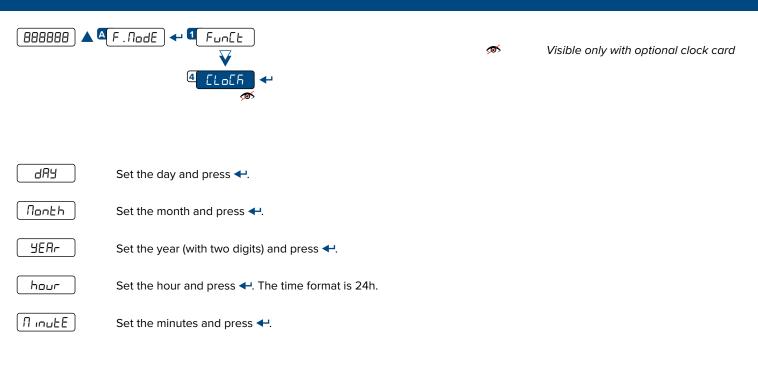
## **Restoring factory settings**



The transmitter is initialized and the default parameters (indicated by the  $\clubsuit$  symbol) are activated. Pressing  $\checkmark$  the display shows "*dFLEr*" confirm further with  $\checkmark$  or exit by pressing another key.

The actual activation of the default parameters is performed by saving the settings (SRUEP) while exiting the menu.

### Date and time setting



The date and time format is: DD/MM/YY, HH:MM:SS (24h),



Indicates repeated pressing of the vey.



Parameter visible only under certain conditions.

Parameter or menu subject to approval.

Default value of the parameter.





## Alarms

PrEC         Displayed if you try to calibrate a point without first confirming the number of calibration points (n EP).           Er. Ab.t         Calibration error: unstable weight during point acquisition.           Er. A.1         Calibration error: during the acquisition of a calibration point a NULL value was read from the converter.           Error. H.1         Calibration error: during the acquisition of the calibration parameters of channel H, where H indicates the number of the channel to which the error refers.           adEr. H         Calibration error: The acquired calibration point is to there is an error in the calibration parameters of channel H, where H indicates the number of the channel to which the error refers.           Err. 11         Calibration error: The acquired calibration point is P 1/EP 2 / EP 3 is equal to the zero point (EP).           Err. 12         Calibration error: The acquired calibration point is to low was used; it is recommended to use a weight of at least half the scale's capacity.           Err. 13         Scale to be calibrated (we recomment resetting the transmitter to the factory default "dEFA" settings before proceeding).           Error 37         Scale to be calibrated (we recomment resetting the transmitter to the factory default "dEFA" settings before is the calibration point is equal to the zero point.           C.Fr 37         Negetive internal points below the minimum value were calculated during calibration:           C.Fr 37         Internal points below the minimum value were calculated during calibration:           A.Fror         Hard	Alarm	Description			
ErPabCalibration error: during the acquisition of a calibration point a NULL value was read from the converter.Err. H. 1Calibration error: during the acquisition of a calibration point a NULL value was read from the converter.Err. H. 1Calibration error: during the capacity of channel H is not set, or there is an error in the calibration parameters of channel H, where H indicates the number of the channel to which the error refers.euEr. HCalibration error: a sample weight that is too low was used; it is recommended to use a weight of at least half the scale's capacity.Er12Calibration error: The acquired calibration point (P 1/EP 2 / EP 3) is equal to the zero point (PD).Er37Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFAu" settings before proceeding).Er39Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFAu" settings before proceeding).E. f35Negative internal points were calculated during calibration: • the calibration point is below the zero point; • the calibration point is below the zero point; • the calibration point is equal to the zero point; • the calibration point is equal to the zero point; • the calibration point is equal to the transmitter does not detect the presence of the card when the abiti equal to the zero point; • to coliphic acquirity and the transmitter does not detect the presence of the card when the abiti equal to the zero point; • to coliphic acquirity and on. The E-rol function is set automatically, but not saved in the setup environment.b. forHardware error: software not compatible with the installed hardware.R. f. f.rYou are trying to print with an unstable weight. • ar	Prec	Displayed if you try to calibrate a point without first confirming the number of calibration points ( $\neg E^p$ ).			
Err , H, JError that occurs if the capacity of channel H is not set, or there is an error in the calibration parameters of channel H, where H indicates the number of the channel to which the error refers. $adEr + H$ Error that occurs if the capacity of channel H is not set, or there is an error in the calibration parameters of channel H, where H indicates the number of the channel to which the error refers. $Er + H$ Calibration error: a sample weight that is too low was used; it is recommended to use a weight of at least half the scale's capacity. $Er + I2$ Calibration error: The acquired calibration point ( $EP + I/EP 2 / EP 3$ ) is equal to the zero point ( $EP0$ ). $Er + 33$ Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding). $Er + 33$ Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding). $Er + 35$ Negative internal points were calculated during calibration: • the calibration point is below the zero point. • the calibration point is below the zero point. • the calibration point is below the minimum value were calculated during calibration: • the calibration point is below the recompetities. $E.Er. + 37$ Internal points below the minimum value were calculated during calibration: • the calibration point is equal to the zero point. • to calibrate on the labil memory is erabled and the transmitter does not detect the presence of the card when the power is turned on. The $E \rightarrow U$ function is set automatically, but not saved in the setup environment. $B.Erc + 37$ Piniting in progress (printer serial port busy) or transmitter valuing to transmit a print to PC. unspect to the division. $B.Erc + 37$ Vou are	Er .Not	Calibration error: unstable weight during point acquisition.			
PF * N · 1       channel H, where H indicates the number of the channel to which the error refers.         adEr H       channel H, where H indicates the number of the channel to which the error refers.         Er H       Calibration error: a sample weight that is too low was used; it is recommended to use a weight of at least half the scale's capacity.         Er H       Calibration error: The acquired calibration point ( $F^{P} / I / F^{P} / F^{P}$ ) is equal to the zero point ( $F^{P}$ ).         Er 31       Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).         Er 33       Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).         Er 33       Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).         Er 34       Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).         Er 4 39       Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).         E. Fr - 37       Negative internal points below the minimum value were calculated during calibration: <ul> <li>the signal is negative (check the connections).</li> <li>the signal is negative (check the connections).</li> <li>the calibration point is equal to the zero point.</li> <li>too high a capacity has been set with respect to the division.</li> <li>ket calibration error software noro: software pro</li></ul>	ErPnt	Calibration error: during the acquisit	ion of a calibration point a NULL value was read from the converter.		
able in the image in the im	Err.H.l				
Prima       the scale's capacity.         Er       Ide       Calibration error: The acquired calibration point ( <i>FP</i> 1/ <i>FP</i> 2/ <i>FP</i> 3) is equal to the zero point ( <i>FP</i> ).         Er       31       Scale to be calibrated (we recomment resetting the transmitter to the factory default "d <i>FFAu</i> " settings before proceeding).         Er       32       Scale to be calibrated (we recomment resetting the transmitter to the factory default "d <i>FFAu</i> " settings before proceeding).         Er       33       Negative internal points were calculated during calibration: <ul> <li>the calibration point is below the zero point;</li> <li>the calibration po</li></ul>	oUEr H	Error that occurs if the capacity of channel H is not set, or there is an error in the calibration parameters of			
Er31Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).Er39Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFRu" settings before proceeding).Er. 39Negative internal points were calculated during calibration: • the calibration point is below the zero point; • the calibration point is below the connections).E.Er30Internal points below the minimum view ever calculated during calibration: • the calibration point is equal to the zero point; • to ohigh a capacity has been set with respect to the division.bd.ErrHardware error: software not compatible with the installed hardware.RL.ErrDisplayed when the alibi memory is =ubled and the transmitter does not detect the presence of the card when the power is turned on. The Zerif function is set automatically, but not saved in the setup environment.bd59You are trying to print with an unstable weight.un.od/ErYou are trying to print with the weight in underload / overload.cress.ErYou are trying to print with a non-power weight (less than or equal to zero).nefs.ErYou are trying to print with a non-power weight (less than or equal to zero).nefs.ErYou are trying to print with a non-power weight (less than or equal to zero).nefs.ErYou are trying to print with a non-power weight (less than or equal to zero).na.fl.on5Weight not passed by net 0 or instability is converting the unit of measurement.canduYou are trying to print with a non-power weight (less than or equal to zero).na.fl.frYou are trying to print with a non-power the w	Er II				
Er       31       proceeding).         Er       39       Scale to be calibrated (we recomment resetting the transmitter to the factory default "dEFRu" settings before proceeding).         Er. Fr36       Negative internal points were calculated during calibration: <ul> <li>the calibration point is below the zero point;</li> <li>the calibration point is equal to the zero point;</li> <li>the calibration point is equal to the zero point;</li> <li>the calibration point is equal to the zero point;</li> <li>to to high a capacity has been set with respect to the division.</li> </ul> bl:Err37       Internal points were not compatible with the installed hardware.         Rt. Err.       Hardware error: software not compatible with the installed hardware.         Rt. Err.       Displayed when the alibi memory is enabled and the transmitter does not detect the presence of the card when the power is turned on. The Carl function is set automatically, but not saved in the setup environment.         bu59       Printing in progress (printer serial port busy) or transmitter waiting to transmit a print to PC.         un.duEr       You are trying to print with an unstale weight.         un.duEr       You are trying to print with the weight in underload / overload.         errore       The weight is underloaded.       Approved transmitter: -100 divisions.         errore       You are trying to print with a non-positive gross weight (less than or equal to zero).         nefr. Err       You are trying	Er IZ	Calibration error: The acquired calib	ration point ( $EP I/EP 2/EP 3$ ) is equal to the zero point ( $EPD$ ).		
Er       30       proceeding).         E.Er 33       Negative internal points were calculated during calibration:	Er 37				
L.Er 36 <ul> <li>the calibration point is below the zero point;</li> <li>the signal is negative (check the connections).</li> </ul> L.Er 31       Internal points below the minimum value were calculated during calibration: <ul> <li>the calibration point is equal to the zero point;</li> <li>too high a capacity has been set with respect to the division.</li> </ul> hd.Err             Hardware error: software not compatible with the installed hardware.               RL.Err             Displayed when the alibi memory is embled and the transmitter does not detect the presence of the card when the power is turned on. The Lond function is set automatically, but not saved in the setup environment.               bu59 <li>Printing in progress (printer serial port busy) or transmitter waiting to transmit a print to PC.</li> un.ol/Er             You are trying to print with an unstable weight.               un.ol/Er <li>The weight is overloaded (9 divisions)</li> <ul> <li>approved transmitter: -100 divisions.</li> <li>Gro S.Er</li></ul>	Er 39				
L.Er ∃1 <ul> <li>the calibration point is equal to the zero point;</li> <li>too high a capacity has been set with respect to the division.</li> </ul> hB.Err       Hardware error: software not compatible with the installed hardware.         RL.Err       Displayed when the alibi memory is enabled and the transmitter does not detect the presence of the card when the power is turned on. The ∠and/function is set automatically, but not saved in the setup environment.         bu59       Printing in progress (printer serial portugation is set automatically, but not saved in the setup environment.         un.dlEr       You are trying to print with an unstate weight.         un.dlEr       You are trying to print with the weight in underload / overload.         un.dlEr       The weight is overloaded (9 divisions.         ner5.Fr       You are trying to print with a non-post regress weight (less than or equal to zero).         nc5.Fr       You are trying to print with a non-post weight (less than or equal to zero).         nc7.Fr       You are trying to print with a non-post weight (less than or equal to zero).         nc8.fer       You are trying to print with a non-post weight (less than or equal to zero).         nc9.un5       Weight not passed by net 0 or instate is converting the unit of measurement.         LonU       You are trying to print while the transmitter is converting the unit of measurement.         LonU       You are trying to print while the transmitter.	E.Er36	<ul><li>Negative internal points were calculated during calibration:</li><li>the calibration point is below the zero point;</li></ul>			
RL.ErrConstruction of the card of the card of the transmitter does not detect the presence of the card when the power is turned on. The Construction is set automatically, but not saved in the setup environment.bu59Printing in progress (printer serial possible dard the transmitter waiting to transmit a print to PC.un5tRbYou are trying to print with an unstable weight.un.oblErYou are trying to print with the weight in underload / overloadThe weight is overloaded (9 divisions)The weight is underloadedThe weight is underloadedThe weight is underloadedYou are trying to print with a non-possible grows weight (less than or equal to zero).nc5t.FrYou are trying to print with a non-possible net weight (less than or equal to zero).nc7t.frYou are trying to print with a non-possible net weight (less than or equal to zero).nc8t.frYou are trying to print with a non-possible net weight (less than or equal to zero).nc9t.frYou are trying to print with a non-possible net weight (less than or equal to zero).nc9t.frYou are trying to print with a non-possible net weight (less than or equal to zero).nc9t.frYou are trying to print with a non-possible net weight (less than or equal to zero).nc9t.frYou are trying to print while the transmitter is converting the unit of measurement.EonJUYou are trying to print while the transmitter is converting the unit of measurement.Err.fl.fhCommunication problems with the ck card of the transmitter.	[.Er37	the calibration point is equal to the zero point;			
HL.Err       when the power is turned on. The LonU function is set automatically, but not saved in the setup environment.         bu59       Printing in progress (printer serial power) busy) or transmitter waiting to transmit a print to PC.         un.5LRb       You are trying to print with an unstable weight.         un.aUEr       You are trying to print with the weight in underload / overload.          The weight is overloaded (9 divisions over the maximum capacity).          The weight is underloaded.         Mon-approved transmitter: -100 divisions.         free S.Er       You are trying to print with a non-postive gross weight (less than or equal to zero).         nEr.Err       You are trying to print with a non-postive net weight (less than or equal to zero).         ne.0.un5       Weight not passed by net 0 or instability.         Condl       You are trying to print while the transmitter is converting the unit of measurement.         Err.ELF       Communication problems with the ck ck card of the transmitter.	ны.Егг				
unSERbYou are trying to print with an unstable weight.un.allErYou are trying to print with the weight in underload / overload.The weight is overloaded (9 divisions)The weight is overloaded (9 divisions).The weight is underloaded.Approved transmitter: -100 divisions. Non-approved transmitter: -maximum capacity -9 divisions.EraS.ErYou are trying to print with a non-postive gross weight (less than or equal to zero).nEr.ErrYou are trying to print with a non-postive net weight (less than or equal to zero).na.0.un5Weight not passed by net 0 or instability.ConflYou are trying to print while the transmitter is converting the unit of measurement.Err.LLFCommunication problems with the transmitter.	RL.Err				
un.ad/ErYou are trying to print with the weight in underload / overloadThe weight is overloaded (9 divisions over the maximum capacity)The weight is underloaded.Approved transmitter: -100 divisions. Non-approved transmitter: -maximum capacity -9 divisions.Gra5.ErYou are trying to print with a non-positive gross weight (less than or equal to zero).nEr.ErrYou are trying to print with a non-positive net weight (less than or equal to zero).na.0.un5Weight not passed by net 0 or instability.CanUYou are trying to print while the transmitter is converting the unit of measurement.Err.ELFCommunication problems with the clock card of the transmitter.	6059	Printing in progress (printer serial port busy) or transmitter waiting to transmit a print to PC.			
Image: A provide a principal princi	unSERb	You are trying to print with an unstable weight.			
Image: Approved transmitter: -100 divisions.         Image: Approved transmitter: -100 divisi	un . oUEr	You are trying to print with the weight in underload / overload.			
The weight is underloaded.       Non-approved transmitter: -maximum capacity -9 divisions.         Gr o 5 . Er       You are trying to print with a non-positive gross weight (less than or equal to zero).         nEr . Err       You are trying to print with a non-positive net weight (less than or equal to zero).         no . D . un 5       Weight not passed by net 0 or instability.         ConU       You are trying to print while the transmitter is converting the unit of measurement.         Err . ELF       Communication problems with the clock card of the transmitter.		The weight is overloaded (9 divisions over the maximum capacity).			
Gra5.Er       You are trying to print with a non-positive gross weight (less than or equal to zero).         nEr.Err       You are trying to print with a non-positive net weight (less than or equal to zero).         no.0.un5       Weight not passed by net 0 or instability.         EonU       You are trying to print while the transmitter is converting the unit of measurement.         Err.ELF       Communication problems with the clock card of the transmitter.		The weight is underloaded.			
nEr.Err       You are trying to print with a non-positive net weight (less than or equal to zero).         no.D.un5       Weight not passed by net 0 or instability.         ConU       You are trying to print while the transmitter is converting the unit of measurement.         Err.ELF       Communication problems with the clock card of the transmitter.		You are trying to print with a non-po			
LonU       You are trying to print while the transmitter is converting the unit of measurement.         Err.ELF       Communication problems with the clock card of the transmitter.					
Err.ELF     Communication problems with the clock card of the transmitter.	no . 0 . un5				
	ConU	You are trying to print while the transmitter is converting the unit of measurement.			
EEL .Err     Signal anomaly: check the connection of the cells.	Err.ELR	Communication problems with the clock card of the transmitter.			
	EEL.Err	Signal anomaly: check the connection of the cells.			



**•** 

6



Press the key during the start-up procedure.

SAVING THE PARAMETERS:

Press the C key several times, until the display shows SRUEP. Press the ← key to confirm.



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This publication, or any part of it, may not be reproduced without written permission from the Manufacturer. All information in this manual is based on the data available at the time of its publication; the Manufacturer reserves the right to make changes to its products at any time, without notice and without incurring any penalty. We therefore recommend that you always check for updates. The person responsible for the use of the scale must ensure that all safety regulations in force in the country of use are applied, ensure that the scale is employed in accordance with the intended use and avoid any dangerous situation for the user. The Manufacturer declines all responsibility for any weighing errors.



**Notes** 





**Notes** 









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Stamp of the authorized service center